Tensor Networks, Fundamental Theorems, and Computational Complexity





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joint work with Arturo Acuaviva, Visu Makam, Harold Nieuwboer, David Pérez-García, Friedrich Sittner, Freek Witteveen (QIP 2023, arXiv:2209.14358)

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Complexity of many-body quantum physics



Many-body quantum states have exponentially large description:

$$|\Psi\rangle = \sum_{i_1,\ldots,i_n} \Psi_{i_1,\ldots,i_n} |i_1,\ldots,i_n\rangle$$

In practice, entanglement local \rightsquigarrow compact description:

Start with local entangled pairs...

... and "glue" by applying local transformations:

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What is a tensor network?

Given a tensor

$$T = \sum_{i,j,k} T_{ijk} \ket{i} \ket{j} \ket{k}$$

we represent it graphically as



Contraction of tensors is shown graphically as



The tensor network tool box



Numerical tool on classical and quantum computers

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$$\cdots - - - - - - - - = |00 \cdots 00\rangle + |11 \cdots 11\rangle$$

Quantum cellular automata:

Unitary, but not a quantum circuit!

• An example from TCS: $= \sum_{i,j,k} A_{ij} B_{jk} C_{ki} = tr(ABC)$

and hence

is the matrix multiplication tensor.

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1D: Matrix product states (MPS)

Consider 3-leg tensor M with bond dimension D and physical dimension d:



This determines a quantum state on any *n* sites:

Its coefficients are $\langle i_1, \ldots, i_n | M_n \rangle = \operatorname{tr}(M^{(i_1)}M^{(i_2)}\cdots M^{(i_n)})$, hence the name.

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Computing with tensor networks

Essentially all computations amount to tensor contractions:



Computational complexity: Easy in 1D. In principle, hard in 2D and higher.

2D: Projected entangled pair states (PEPS)

Consider 5-leg tensor T with bond dimension D and physical dimension d:



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Geometry vs. entanglement

 $S(A) = -\operatorname{tr} \rho_A \log \rho_A$



- Any tensor network satisfies an area law, determined by its geometry.
- In 1D, low-energy states of local gapped quantum systems satisfy area law and have accurate MPS representations [Hastings].
- ► These can be found in polynomial time [Landau-Vazirani-Vidick, Arad et al].
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Fundamental theorems

Given two tensors, when do they generate the same tensor network state?

Easy to find such situations! MPS:

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Fundamental theorem for MPS



In 1D, gauge symmetry and taking limits is the only redundancy. We can efficiently pick canonical form. It is unique up to *unitaries* & satisfies:

Fundamental Theorem of MPS (Cirac–PG–Schuch, de las Cuevas)

Two tensors *M* and *N* give rise to the same quantum states $|M_n\rangle = |N_n\rangle$ for all system sizes *n* if and only if they have same canonical forms.

Many applications!

- Classification of symmetries and topological phases
- Classification of quantum cellular automata
- Better-behaved numerics

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Illustration: Classification of symmetries

Suppose *M* is tensor with global (on-site) symmetry for any system size *n*:

Fundamental theorem implies that there is unitary U such that

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Computational complexity

In particular, " $|M_n\rangle = |N_n\rangle$ for all *n*?" can be decided in polynomial time.



Bad news: For PEPS, " $|T_{m,n}\rangle = |S_{m,n}\rangle$ for all *m*, *n*?" is undecidable!

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Intuition: There are many inequivalent surfaces in 2D!

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Our proposal: The minimal canonical form

Group action of $G = GL(D) \times GL(D)$:



Define minimal canonical form of PEPS tensor T by minimizing ℓ^2 -norm:

$$T_{\min} := \operatorname{argmin} \{ \|S\|_2 : S \in \overline{G \cdot T} \}.$$

- Closure is needed so that minimum is attained, but also natural since taking limits is allowed.
- ▶ First rigorous canonical form in 2D (+ similarly works in higher dim)!

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What does it characterize?

Recall the group action of $G = GL(D) \times GL(D)$:



We say T, T' are gauge equivalent if $\overline{G \cdot T}$ and $\overline{G \cdot T'}$ intersect. This implies that they give the same many-body states!

Result (Canonical form)

- **①** The minimal canonical form exists and is unique up to $U(D) \times U(D)$.
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Fundamental Theorem of PEPS

Two tensors ${\cal T}$ and ${\cal T}'$ give rise to the same tensor network state on any admissible graph Γ



if and only if they are gauge equivalent, so if and only if they have the same minimal canonical forms.

In fact, e^{O(D²)} vertices suffice to distinguish two PEPS tensors, and e^{Ω(D)} vertices are necessary. For MPS, we note O(D) vertices suffice.

Decidability

In particular, " $|T_{\Gamma}\rangle = |T_{\Gamma}'\rangle$ for all graphs Γ ?" is decidable. \odot

Intuition: Undecidability for $|T_{n,m}\rangle$ reduces to periodic tiling problem. Its undecidability in turn relies on existence of aperiodic tile sets such as:

There exist $I \neq 0$ such that all $|I_{n,m}\rangle = 0$, but no algorithm can recognize them! [Scarpa et al] However, if allow arbitrary graphs (topologies) this distinction collapses!

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How to characterize the canonical form?

We show that a tensor T



is in minimal canonical form if and only if



This means the state $\rho = |T\rangle \langle T|$ satisfies $\rho_{\text{right}} = \overline{\rho_{\text{left}}} \& \rho_{\text{bottom}} = \overline{\rho_{\text{top}}}$. Physical interpretation?

A field of mathematics that studies equivalence for "nice" actions of group G on vector space V. In our case:

$$\label{eq:GL} \begin{split} \mathcal{G} &= \operatorname{GL}(D) \quad \text{and} \quad \mathcal{V} = \mathsf{MPS} \text{ tensors of fixed format}, \\ \mathcal{G} &= \operatorname{GL}(D) \times \operatorname{GL}(D) \quad \text{and} \quad \mathcal{V} = \mathsf{PEPS} \text{ tensors of fixed format}. \end{split}$$

Notion of equivalence: $\overline{G \cdot v}$ and $\overline{G \cdot v'}$ intersect. \odot GIT tells us:

- Minimum norm vectors unique up to unitaries. [Kempf-Ness]
- Equivalent iff P(v) = P(v') for all *G*-invariant polynomials *P*. [Mumford]

What are the invariant polynomials in our case? Quantum states!

 $P(M) = \langle i_1, \dots, i_n | M_n \rangle$ for $n = \tilde{O}(D)$. New perspective gives stronger results!

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Algorithms for the minimal canonical form

Given a tensor T, how to compute T_{min} ? Nontrivial, even for MPS!



Result (Algorithms)

For fixed bond dimension D, can approximate T_{min} in polynomial time.

Combines computer science ideas from the solution of *Paulsen's problem* with recent results on optimization on groups (*operator, tensor scaling*).

Key idea: $g \mapsto ||g \cdot v||$ is convex along geodesics of curved space arising from noncommutative group. Accordingly, local algorithms can find canonical form. Versatile framework, many applications. [Bürgisser-...-w-wigderson]

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Summary and outlook

Tensor networks describe high-dimensional data succinctly. Applications from physics to numerics to computer science.

Fundamental theorems and canonical forms are key tools. We propose first rigorous general such tools beyond 1D.

To achieve this, we connect tensor networks to powerful tools from geometric invariant theory and recent progress on optimization algorithms in theoretical computer science.

Many exciting open questions: Faster algorithms for large bond dimension? Flexible framework – how about other tensor networks? Connection to topological order? Impact on numerics? **Thank you for your attention**!





