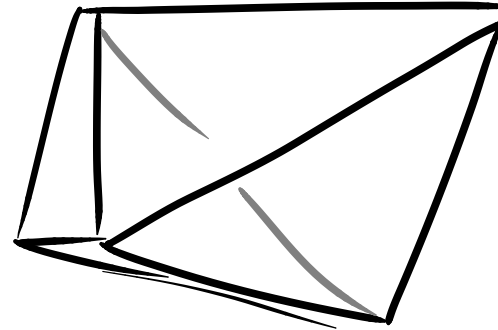
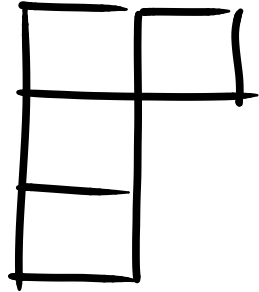


Simons Reunion Workshop, Berkeley (December 2015)



On the **computational complexity** of the membership problem for **moment polytopes**

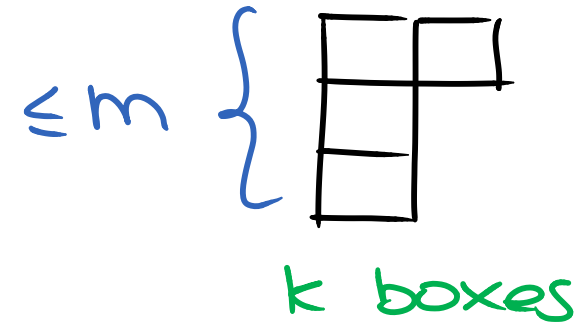
Michael Walter, Stanford University

joint work with P. Bürgisser, M. Christandl, K. Mulmuley; M. Vergne

Notation

Young diagram λ :

- row lengths $\lambda_1 \geq \dots \geq \lambda_m \geq 0$
- partition of k into $\leq m$ parts



They parametrize the irreducible representations of:

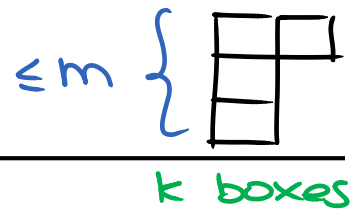
Symmetric group S_k

Specht module $[\lambda]$

General linear group $GL(m)$

Weyl module V_λ^m

Kronecker coefficients



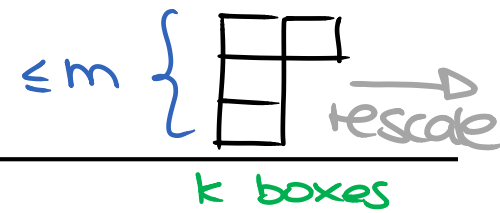
$$[\lambda] \otimes [\mu] = \bigoplus_{\nu} g_{\lambda\mu\nu} [\nu]$$

Many interesting connections to other areas of mathematics as well as applications (quantum physics, geometric complexity theory), in part via

$$\text{Sym}^k(\mathbb{C}^m \otimes \mathbb{C}^m \otimes \mathbb{C}^m) = \bigoplus_{\lambda\mu\nu} g_{\lambda\mu\nu} V_{\lambda}^m \otimes V_{\mu}^m \otimes V_{\nu}^m$$

Despite 75+ years of history, many properties remain mysterious!

Kronecker coefficients: asymptotics

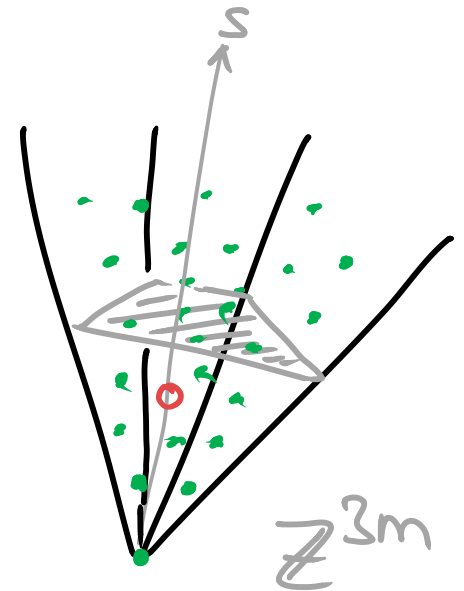


$$G(m) = \{(\lambda, \mu, \nu) : g_{\lambda \mu \nu} > 0\}$$

Asymptotic support is **convex cone**: [Mumford], [Kirwan]

- outside: $g \equiv 0$ inside: $\exists s : g_{s\lambda, s\mu, s\nu} > 0$

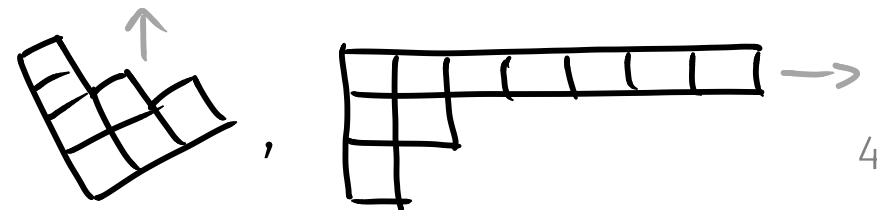
in general, $s > 1$: failure of saturation, "holes"!



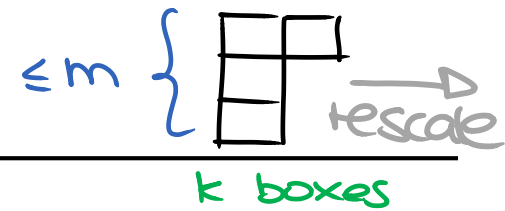
- piecewise quasi-polynomiality

[Guillemin-Sternberg], [Meinrenken-Sjamaar]

Various other asymptotics have been studied:

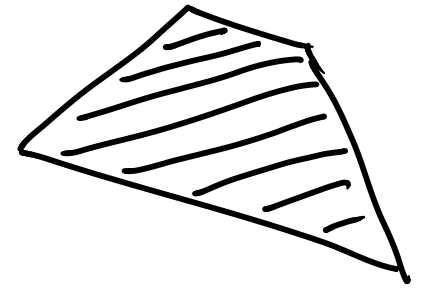


The Kronecker polytopes



$$\Delta(m) = \left\{ \frac{(\lambda, \mu, \nu)}{k} : g_{\lambda \mu \nu} > 0 \right\}$$

...is a convex polytope: the **Kronecker polytope**.



More generally: Define **moment polytope**

$$\Delta_G(M) = \left\{ \frac{\lambda}{k} : V_\lambda \subseteq \text{Sym}^k(M) \right\}$$

where G compact connected Lie group, M unitary representation.

E.g., Littlewood-Richardson coefficients give rise to Horn polytopes.

$$\Delta(m) = \left\{ \frac{(\lambda, \mu, \nu)}{k} : g_{\lambda \mu \nu} > 0 \right\}$$

1. Effective “combinatorial” description of moment polytopes

[Vergne-W., 2014]

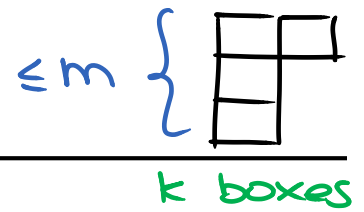
2. Computational complexity: NP \cap coNP.

[Bürgisser-Christandl-Mulmuley-W., 2015]

Motivation: Interest in computing moment polytopes in practice, quantum marginal problem; understand hardness vs. failure of saturation (cf. [BIH])

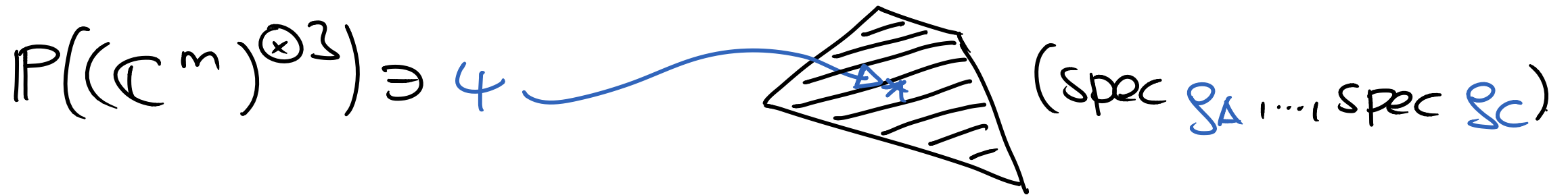
1. Inequalities for moment polytopes

Geometric description



$$\Delta(m) = \left\{ \frac{(\lambda, \mu, \nu)}{k} : g_{\lambda \mu \nu} > 0 \right\}$$

can also be described in **geometric** terms via “moment map”



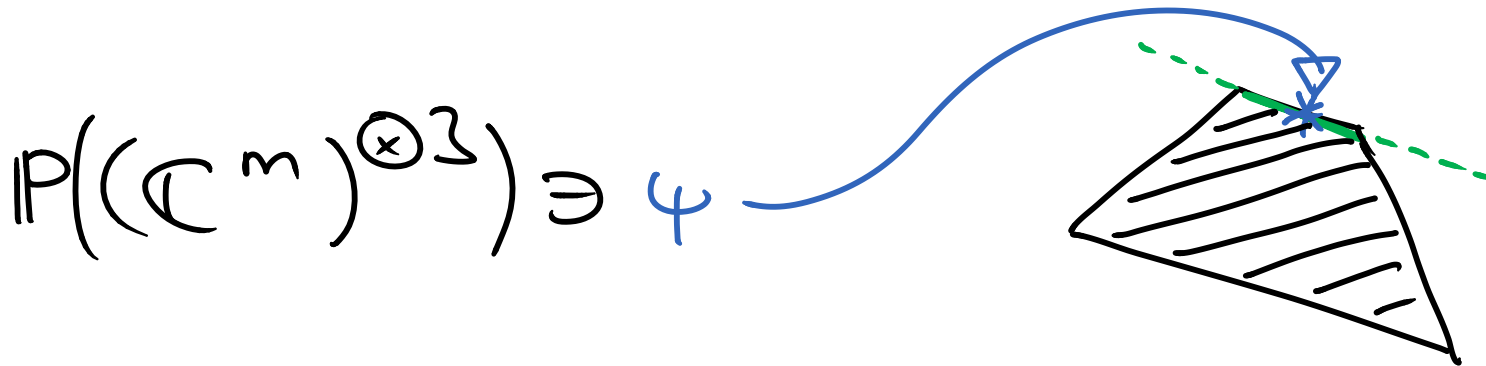
where $\text{tr } \mathfrak{g}_A X_A = \langle \psi | X_A \otimes I \otimes I | \psi \rangle$ etc. (“reduced density matrices”)

Proof via basic GIT. \sim Quantum marginal problem, q. version of discrete tomography!
 Similar: Horn polytopes vs. spectra of Hermitian matrices with $A + B + C = 0$.

Basic idea

$$H \cdot \nu = (H_A, H_B, H_C) \cdot (r_A, r_B, r_C) \stackrel{!}{\geq} z$$

We derive necessary conditions on H and z to be a valid inequality by studying the moment map in first and second order (geometric picture):



Result can be expressed purely in terms of representation-theoretic data!

Roots and weights

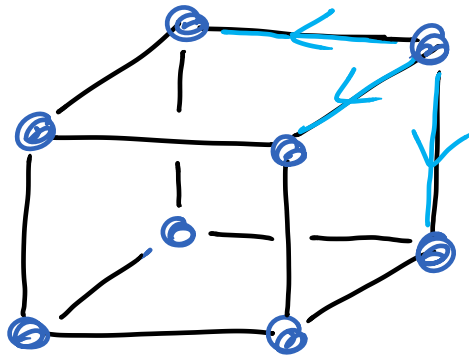
$$G = \mathrm{SU}(m)^3 \hookrightarrow M = (\mathbb{C}^m)^{\otimes 3}$$

Negative roots: $N = \{ (e_i - e_j, 0, 0) : i > j \} \cup \dots$

Weights: $\Omega = \{ (e_i, e_j, e_k) \}$

$$e_i = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

E.g., $m=2$:



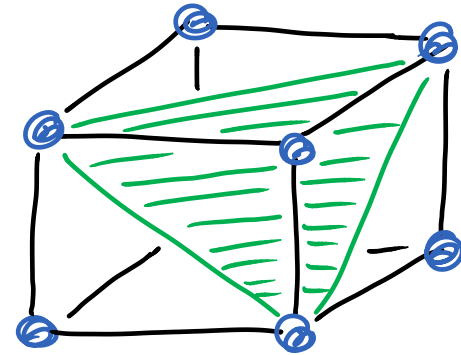
negative roots of $\mathrm{SU}(2)^3$
weights of $\mathbb{C}^2 \otimes \mathbb{C}^2 \otimes \mathbb{C}^2$

Inequalities for the Kronecker polytopes

[Vergne-W., 2014]

Theorem: The Kronecker polytope $\Delta(m)$ is cut out by inequalities $H \cdot r \geq z$ satisfying the following conditions (“Ressayre elements”):

• $\Omega(H=z) = \{ \rho \in \Omega : H \cdot \rho = z \}$ span hyperplane



• $N(H < 0) = \{ \alpha \in N : H \cdot \alpha < 0 \}$

have same cardinality, and

$\Omega(H < z) = \{ \omega \in \Omega : H \cdot \omega < z \}$

$$\det \left[\sum_{\rho \in \Omega(H=z)} X_{\rho} \delta_{\alpha+\rho=\omega} \right]_{\omega, \alpha} \neq 0$$

Numerical results

[Vergne-W., 2014]

Conditions are concrete → effective in low dimensions (can go beyond what had been computed before).

#	H_A	H_B	H_C	z
1	$(-5, -1, 3, 3)$	$(-5, 3, 3, -1)$	$(5, 1, -3, -3)$	5
2	$(-5, -1, 3, 3)$	$(1, -3, -3, 5)$	$(3, 3, -1, -5)$	5
3	$(-5, 3, -1, 3)$	$(-5, 3, -1, 3)$	$(5, 1, -3, -3)$	5
..... etc.....				

However: Number of inequalities grows rapidly!

(a, b, c)	$(2, 2, 2)$ [43]	$(3, 3, 3)$ [45]	$(4, 4, 4)$
Inequalities	9 (3)	114 (25)	1749 (323)
Facets	6 (2)	45 (10)	270 (50)
Extreme Rays	5 (3)	33 (11)	328 (65)

Recall the last condition:

$$\det \left[\sum_{\varphi \in \Omega(\mathcal{H}=\mathcal{Z})} X_{\varphi} \delta_{\alpha+\varphi=\omega} \right]_{\omega, \alpha} \neq 0$$

This "determinant polynomial" is highest weight vector (w.r.t. subgroup).

Thus determines point in (lower-dimensional) moment polytope:

$$\kappa_{\mathcal{H}, \mathcal{Z}} \in \Delta_{G'}(\mathcal{N}')$$

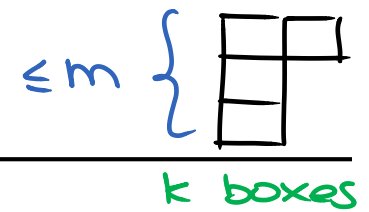
necessary condition!

In the case of the Horn polytopes, this reduces precisely to the recursive definition of Horn's inequalities (i.e., also sufficient).

2. Computational complexity



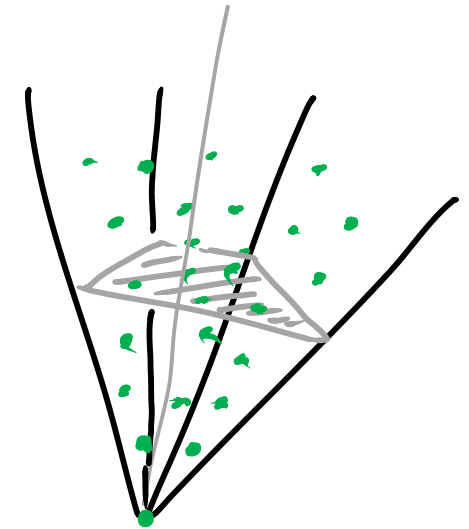
Kronecker polytopes as a decision problem



KRONPOLYTOPES: Given three Young diagrams as input, decide if

$$\frac{(\lambda, \mu, \nu)}{k} \in \Delta(m) ?$$

Equivalently, decide if $\exists s: g_{s\lambda, s\mu, s\nu} > 0$?



Importantly, the height m is not bounded:

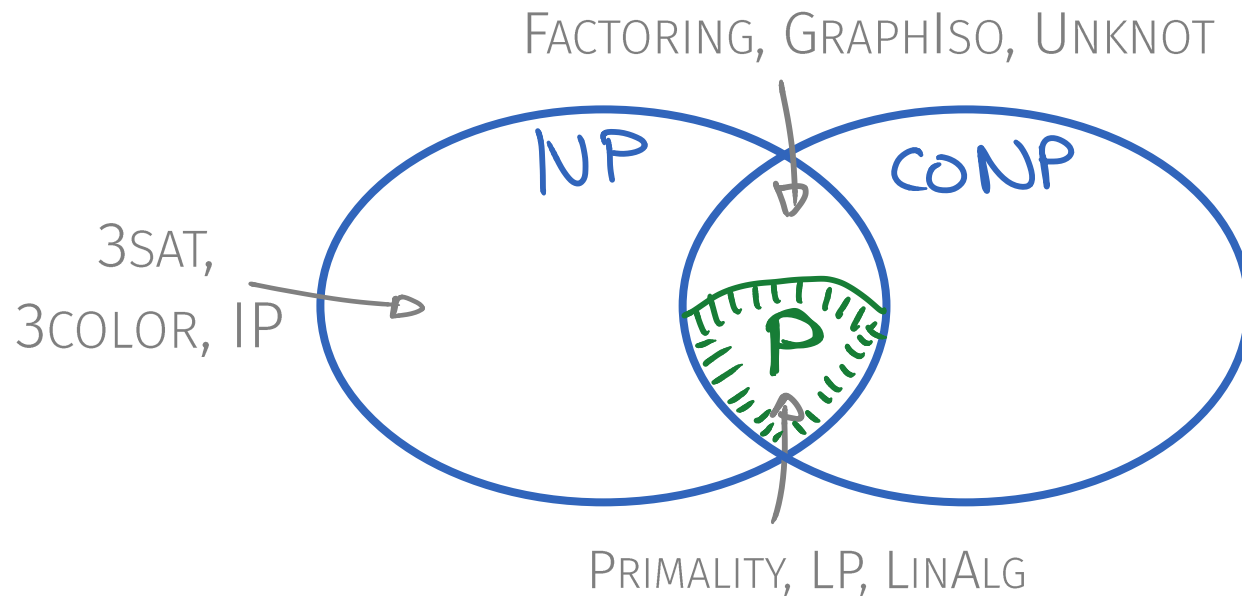
Challenges: No useful bounds on stretching factor s . Quadratically constrained program (NP-hard in general). Large # of Ressayre elements.

The complexity classes P, NP, and coNP

P: There exists an efficient algorithm.

NP: If answer YES then there exists small certificate that can be efficiently verified.

CoNP: If answer NO then there exists small certificate that can be efficiently verified.

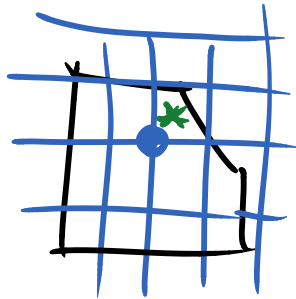


“efficient” = polynomial time; “small” = polynomial bitsize (in the bitsize of the input)

Complexity of Kronecker polytopes [Bürgisser-Christandl-Mulmuley-W., 2015]

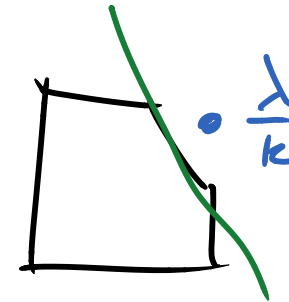
Theorem: The problem KRONPOLYTOPES is in **NP** and **coNP**.

NP: Certificate is vector in $(\mathbb{C}^m)^{\otimes 3}$



Point in polytope can be computed efficiently.
We prove that finite precision is not an issue
(walls of polytope are not too steep).

CoNP: Certificate is Ressayre element (H, z) for separating hyperplane.



Ressayre condition can be checked efficiently
(if also given point at which to evaluate
determinant polynomial).

The bigger picture: classical & quantum complexity

	Kronecker coefficients	Littlewood-R.
COUNTING $g(\lambda, \mu, \nu) = ?$	#P-hard, GapP [Bürgisser-Ikenmeyer, Narayanan] #BQP [Harrow-Christandl-W.]	#P-complete
POSITIVITY $g(\lambda, \mu, \nu) > 0$	NP-hard [Christian's talk] QMA [Harrow-Christandl-W.]	P [Knutsen-Tao], [Blasiak-Mulmuley-Sohoni]
MOMENTPOLYTOPES $\exists \ell: g(\ell \lambda, \ell \mu, \ell \nu) > 0$	NP \cap coNP [this talk]	P

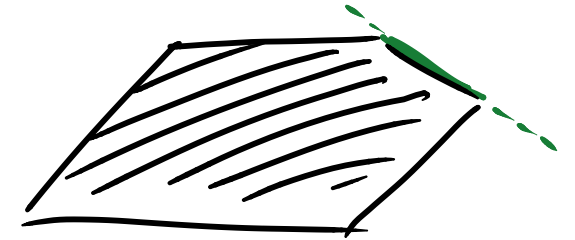
NB: For bounded height (fixed m), all these problems are in P [Christandl-Doran-W.].

Summary

Moment polytopes describe the asymptotic support of representation-theoretic multiplicities. They have been studied in many different contexts (including GCT, quantum physics, ...).

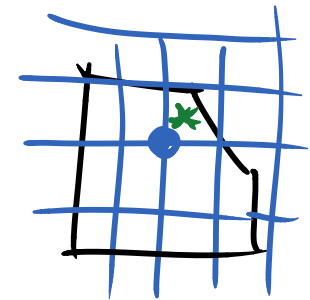
1. Effective “combinatorial” description

[Vergne-W., 2014]



2. Computational complexity: NP \cap coNP.

[Bürgisser-Christandl-Mulmuley-W., 2015]



Results generalize to unitary representations of compact connected Lie groups.

Thank you for your attention