Computing Multiplicities of Lie Group Representations

1000

900

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joint work with Matthias Christandl, Brent Doran (ETH Zürich)





Representation Theory

<u>Representation</u> of a group G: vector space V and group homomorphism $G \to \operatorname{GL}(V)$

$$S_k \curvearrowright \mathbb{C}^k \qquad U(d) \curvearrowright \mathbb{C}^d \qquad G \rightharpoonup \operatorname{Sym}^k(V)$$

For "nice" groups: any representation V can be decomposed into a direct sum of <u>irreducible</u> ones:

$$V = \bigoplus_{\lambda} m_{\lambda} \cdot V_{G,\lambda}$$

The Branching Problem is in P

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<u>Main Result</u>: Christandl, Doran, W. (2012) Poly-time algorithm for any fixed homomorphism $H \rightarrow G$ between compact, connected Lie groups.

> "matrix groups" like O(d), U(d), Sp(n)

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Long history and important applications in mathematics, quantum physics & information theory...

Kostka numbers $T(d) \subseteq U(d)$

Littlewood-Richardson coefficients $U(d) \rightarrow U(d) \times U(d)$

Kronecker coefficients $U(d) \times U(d) \rightarrow U(d^2)$

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matrix multiplication, VP vs.VNP, ...

...as well as in <u>algebraic & geometric complexity theory</u>!

Strassen (1983), Mulmuley & Sohoni (2001)

Poly-time algorithms for fixed d

Cochet (2005)

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Cochet (2005), De Loera & McAllister (2006) Littlewood-Richardson coefficients $U(d) \rightarrow U(d) \times U(d)$

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unified by our result



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Branching Problem for Tori *G*

All irreducible representations are <u>one-</u> <u>dimensional</u> and of the form



$$\begin{pmatrix} z_1 \\ \ddots \\ z_r \end{pmatrix} \cdot \psi = z_1^{k_1} \cdots z_r^{k_r} \psi$$

Labeled by their weight $\omega = (k_1, \ldots, k_r) \in \mathbb{Z}^r$.

Branching Problem for Tori $G = U(1)^r$ $H = U(1)^s$

(Thus) any homomorphism $H \to G$ is of the form

$$\begin{pmatrix} z_1 \\ \ddots \\ z_s \end{pmatrix} \rightarrow \begin{pmatrix} z_1^{k_{1,1}} \cdots z_s^{k_{s,1}} \\ & \ddots \\ & z_1^{k_{r,1}} \cdots z_s^{k_{s,r}} \end{pmatrix}$$

for an integer matrix $\Omega = (k_{i,j}) \in \mathbb{Z}^{s \times r}$.

Conclusion: $V_{G,\omega}|_{H}^{G} = V_{H,\Omega\omega}$ branching problem for tori is trivial

















Summary of Algorithm



Variation

It follows from the proof that m_{μ}^{λ} is <u>"piecewise</u>" ^{Meinrenken &} <u>periodic polynomial function</u>.

polynomials on sublattices

<u>Parametric Algorithm</u>: Can in fact precompute these polynomials *once and for all* (e.g., using parametric version of Barvinok).



Summary (of main part)



Poly-time algorithm for any branching problem of compact connected Lie groups.

<u>Geometric Complexity Theory</u>: Lower bounds from $X \not\subseteq Y$ for certain varieties X, Y (e.g., orbit closure of perm/det of certain size).

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Difficult! Study asymptotics? E.g. asymptotic support (<u>moment polytope</u>).

Ikenmeyer (2011)



Asymptotic growth rate (<u>Duistermaat-Heckman</u> <u>measure):</u>

$$DH_X = \lim_{k \to \infty} \frac{1}{k^{d_X}} \sum_{\lambda} m_{G,X,k}(\lambda) \,\delta_{\lambda/k}$$

<u>Our observation</u>: No crit. for obstructions, since $d_X \neq d_Y$.

Example: SU(2)

The irreducible representations of SU(2) are

 $V_j = \operatorname{Sym}^j(\mathbb{C}^2)$ labeled by their <u>spin</u> j = 0, 1, ...

Maximal torus $\{ \begin{pmatrix} z \\ \overline{z} \end{pmatrix} \}$ is isomorphic to U(1), and its irred. representations labelled by weight $k \in \mathbb{Z}$.

Weights of V_j (all multiplicities are one):



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Goal: decompose a tensor product of SU(2)-irreps:



 $U(1) \times U(1)$

 $\rightarrow SU(2) \times SU(2) \frown V_j \otimes V_k$

I.Weight multiplicities for $V_j \otimes V_k$:





































