Message Passing for Decoding and Inference (§21/25/26)

Recall from Tue/Thu:

① Decoding Problem:

$$S \longrightarrow x^N \longrightarrow y^N \overset{???}{\dashrightarrow} \hat{S}$$

Given channel Q, encoder, and output y^N, how to decode?

* **Maximum likelihood codeword decoder:** Assume $P(S)$ uniform. Given y^N, find s that maximizes $P(S|y^N)$. Eqv: Maximize $P(x^N|y^N)$ over $\mathcal{C} = \{x^N \text{ codeword}\}$. We assume no two s have the same codeword x^N !!!

$$P(x^N|y^N) \overset{\text{Bayes}}{=} \frac{P(y^N|x^N)\,P(x^N)}{P(y^N)} = \cancel{\frac{1}{P(y^N)\cdot\#\mathcal{C}}}\, P(y^N|x^N)\cdot \mathbb{1}[x^N \in \mathcal{C}]$$

Can ignore if y^N known

remember this notation ?

Thus: Given y^N, find x^N that maximizes

$$\boxed{G(x^N) = Q(y_1|x_1)\cdots Q(y_N|x_N)\,\mathbb{1}[x^N\in\mathcal{C}]}$$

* **Bitwise decoder:** Maximize $P(x_i|y^N)$ for each $i=1,\dots,N$. Equivalently: Given y^N, find x_i that maximizes

$$G_i(x_i) := \sum_{\{x_j\}_{j\neq i}} G(x^N)$$

How to avoid having to compute all numbers $G(x^N)$??? exponential in N

e.g. repetition code R_3: $\mathcal{C} = \{000, 111\}$

$$G(x_1,x_2,x_3) = Q(y_1|x_1)\,Q(y_2|x_2)\,Q(y_3|x_3)\,\overbrace{\delta_{x_1,x_2}\,\delta_{x_2,x_3}}^{\text{notation ok?}}$$

e.g. linear code with parity check matrix H: $\mathcal{C} = \{x^N : Hx^N = 0\}$

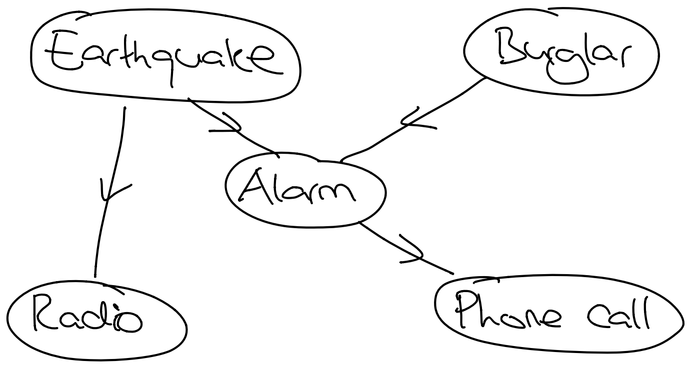
$$G(x^N) = Q(y_1|x_1) \cdots Q(y_N|x_N)\, \mathbb{1}[Hx^N = 0]$$

or, in terms of noise vector $n^N = x^N \oplus y^N$:

$$\tilde{G}(n^N) = P(n_1) \cdots P(n_N) \cdot \mathbb{1}[Hn^N = Hy^N]$$

assuming $Y^N = X^N \oplus N^N$ — i.i.d. noise

② Inference in Bayesian networks:



Assume we have a model

$$P(e,b,r,a,p)$$

$$= P(e)\, P(b)\, P(r|e)\, P(a|eb)\, P(p|a)$$

all functions are known (= model)

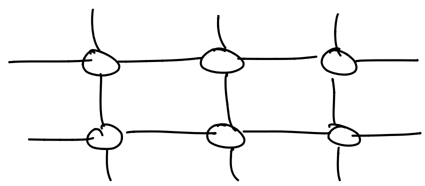
Inference Problems:

$$? = \Pr(B=1 | A=1) = \frac{\Pr(B=1, A=1)}{\sum_b \Pr(B=b, A=1)}$$

↳ enough to compute $\underbrace{\Pr(B=b, A=1)}_{\text{marginal of } B} = \sum_{e,r,p} \underbrace{P(e,b,r,1,p)}_{\text{product of local factors}}$

How to avoid having to first compute $P(e,b,r,1,p)$ for all e,b,r,p?

③ Statistical Physics: Ising model on lattice



* one particle per site with states $x_i \in \{\pm 1\}$

* total energy $E[\{x_i\}] = \sum_{i \sim j} \frac{J}{2}(1 - x_i x_j)$

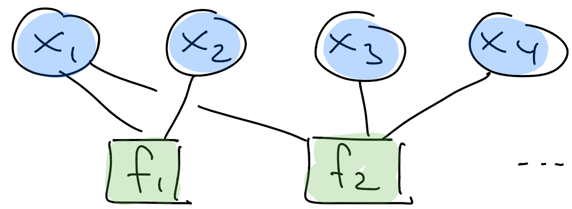
energy cost J if NOT same

ferromagnet if $J>0$

Partition function at temperature T:

$$Z = \sum_{\{x_i\}} e^{-E[\{x_i\}]/T} = \sum_{\{x_i\}} \underbrace{\prod_{i \sim j} e^{-J/2T \cdot (1 - x_i x_j)}}_{\text{product of local factors}}$$

General setup:



$$G(x^N) = \prod_m \underbrace{f_m}_{\text{factor}}(\underbrace{\{x_i\}_{i \in I(m)}}_{\text{subset of variables}})$$

where $x_i \in \mathcal{A}_i$

$$G(x^N) = f_1(x_1, x_2)\, f_2(x_1, x_3, x_4) \cdots$$

Factor graph:

* vertices: x_i for each variable, $\boxed{f_m}$ for each factor
* edge: x_i — $\boxed{f_m}$ if f_m depends on x_i

Problem: Compute marginals ⟶ ① Bitwise decoding, ② Bayesian inference, ...

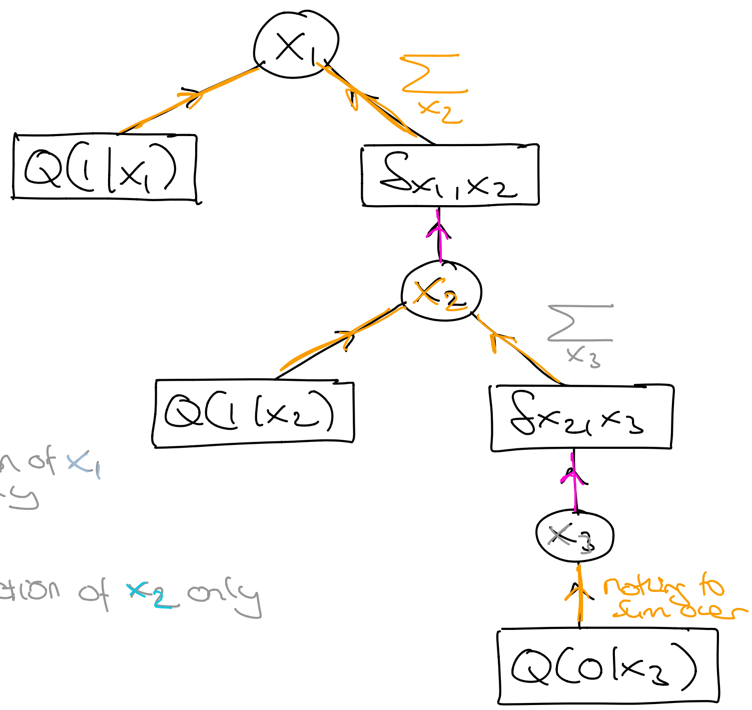
$$\boxed{G_i(x_i) := \sum_{\{x_j\}_{j \neq i}} G(x^N) = \sum_{\substack{x_1, \dots, x_{i-1},\\ x_{i+1}, \dots, x_N}} G(x_1, \dots, x_N)}$$

e.g. for repetition code: If we receive $y^3 = 110$:

$$G(x_1, x_2, x_3) = \delta_{x_1, x_2}\, \delta_{x_2, x_3}\, Q(1|x_1)\, Q(1|x_2)\, Q(0|x_3)$$

* factor graph is tree:

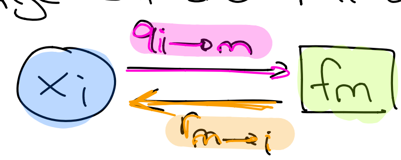
* if rooted at x_1 gives natural "algo" for computing marginal:



$$G_1(x_1) = Q(1|x_1) \underbrace{\sum_{x_2} \delta_{x_1,x_2}\, Q(1|x_2)}_{\text{function of } x_1 \text{ only}} \underbrace{\sum_{x_3} \delta_{x_2,x_3}\, Q(0|x_3)}_{\text{function of } x_2 \text{ only}}$$

⚡ If interested in G_2 or G_3, need to change root and run again

↳ "decentral" message passing algo



Sum-product algorithm ("belief propagation"):

Input: Factor graph & factors $\{f_i\}$ & integer T

① For all edges (x_i)—$\boxed{f_m}$ and all $x_i \in \mathcal{A}_i$:

$$q_{i\to m}(x_i) \leftarrow 1$$

② For T steps:

For all edges (x_i)—$\boxed{f_m}$ and all $x_i \in \mathcal{A}_i$:

$$r_{m\to i}(x_i) \leftarrow \sum_{\{x_j\}_{j\in I(m), j\neq i}} f_m(\{x_j\}_{j\in I(m)}) \cdot \prod_{j\in I(m), j\neq i} q_{j\to m}(x_j)$$

← $I(m)$ = variables that appear in f_m

For all edges (x_i)—$\boxed{f_m}$ and all $x_i \in \mathcal{A}_i$:

$$q_{i\to m}(x_i) \leftarrow \prod_{n\in M(i), n\neq m} r_{n\to i}(x_i)$$

← $M(i)$ = factors that depend on x_i

③ For all vertices (x_i) and all $x_i \in \mathcal{A}_i$:

$$G_i(x_i) \leftarrow \prod_{m\in M(i)} r_{m\to i}(x_i)$$

NB: Messages are functions/tuples! (one real number for each $x_i \in \mathcal{A}_i$)

* Sum-product algo works provably for trees
* computes all G_i at the same time if $T \geq$ diameter of graph.
* in practice also used for general graphs → Lecture 13

  but only a heuristic: problem is NP-hard

Variations:

* Partition function: $Z = \sum_{x^N} G(x^N) = ?$ → ③ physics $\left[Z = \sum_{x_i} G_i(x_i)\right]$
* Maximum: $\max_{x^N} G(x^N) = ?$ → ① ML decoding

[Replace $\sum$ by max ⇝ "max-product" algo $\overset{-\log}{⇝}$ "min-sum" algo]

Outlook

What did we NOT cover?

* Channels with memory
* Multi-user information theory
* More connections to inference, machine learning, etc.
* How to decode barcode from Lecture 1

Bachelor project?

* Quantum information theory → MasterMath course with Maris Ozols
  & Quantum Computing → Courses by Maris (BSc) + Ronald de Wolf (MSc)
* Connections to Cryptography → Course by Chris Schaffner

How to prepare for the exam?

* Learning objectives @ homepage — Course manual NOT up to date!!!
* Lecture notes, homework, problems from the ex. class
* Don't forget to prepare your cheat sheet
* Structure: mix of problems of type ① + ② from HW

THANKS + SEE YOU AGAIN SOON!